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CURRENT DISTRIBUTION IN A PLASMA EROSION OPENING SWITCH
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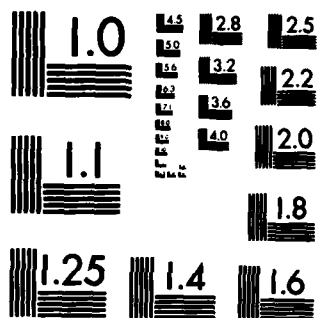
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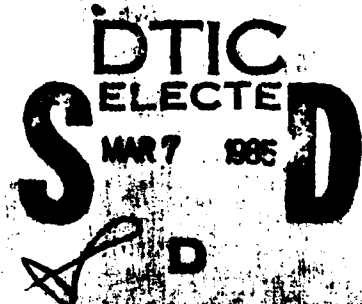
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CURRENT DISTRIBUTION IN A PLASMA EROSION OPENING SWITCH

The Plasma Erosion Opening Switch (PEOS) consists of a low density ($\sim 10^{13} \text{ cm}^{-3}$) plasma injected across a vacuum feed line in a pulsed power generator. The PEOS can conduct high current ($\sim \text{MA}$), open quickly ($< 10 \text{ ns}$), and withstand high voltage ($\sim \text{MV}$). This switching technique has been used in inductive energy storage experiments demonstrating pulse compression, voltage multiplication and power multiplication.¹ The PEOS is used routinely at several laboratories for other types of power conditioning including prepulse suppression,² pulse sharpening³ and multimodule jitter reduction.⁴ In this letter the current flow pattern in a PEOS plasma is determined from magnetic field probe measurements. The current channel in the PEOS plasma broadens as the current through the switch increases. The current channel is wide, $\gg c/\omega_{pe}$, inferring an anomalously high resistivity. The measured current channel width is consistent with a theoretical model that predicts a current density limit imposed by the ion flux to the cathode. Switching occurs when a gap is formed between the plasma and the cathode.

The Gamble I generator⁵ at the Naval Research Laboratory is configured with a PEOS system and a short circuit load as shown in Fig. 1. Three plasma guns⁶ inject a carbon plasma into the region between the screen and the cylindrical center conductor. The generator is fired about $1.5 \mu\text{s}$ later, applying a negative high voltage pulse (-1 MV , 50 ns FWHM) to the center conductor. Currents on the generator (I_G) and load (I_L) sides of the switch are plotted in Fig. 2. The current through the 180 nH storage inductance and PEOS plasma increases to 150 kA in 40 ns , while I_L remains small. During the next 10 ns , I_L increases to 200 kA and the switch current ($I_G - I_L$) becomes small, indicating the switch is open.

Five small probes are used to measure the local magnetic field in the PEOS during fast opening shots. The probes are potted inside 5 mm diameter quartz tubes and inserted into the switching region through the screen. The azimuthal field, $B_\theta(t)$, is measured at the locations shown in Fig. 1. Five axial (z) locations are sampled on a single shot, at the same radial (r) location. The probes are moved to different radial locations to scan the cross section. The probes are calibrated relative to the Rogowski loops that measure I_L and I_G , using data from shots with no plasma injection. In this case, $I = I_G = I_L$ and

$$I \text{ (kA)} = 5r(\text{cm}) B_\theta(\text{kG}). \quad (1)$$

Eq. (1) holds if B_θ is azimuthally symmetric, and gives the total current through a circle of radius r . Measurements of $B_\theta(\theta)$ during fast opening shots indicate that B_θ is reasonably symmetric ($\pm 5\%$) so that Eq. (1) can be used to approximate the current distribution in the plasma.

Probe data, $B_\theta \times 5r(\text{kA})$, are plotted as a function of time in Fig. 3 for $r = 3, 4$ and 5 cm. The corresponding load currents are shown in Fig. 2. The uncertainty in the measurements due to digitizing, calibration, probe orientation and timing is estimated to be ± 20 kA. Experimentally, the probes do not perturb the plasma. The presence of the probes does not affect the measured currents I_G and I_L , and the signal obtained from a given probe is independent of the location of other probes.

The data in Fig. 3 are used to map out current streamlines in the PEOS plasma before, during and after opening. Two times before opening are marked by arrows in Fig. 2 at $t = 16$ and 36 ns. These times correspond to the first nonzero points of the $r = 5$ cm probe signals at $z = 4$ and 6 cm which identify the downstream edge of the current channel. The width of the current channel is determined by comparing adjacent probe signals. For example, at

$t = 36$ ns the downstream edge of the current channel is at $r = 5$ cm, $z = 6$ cm. The 130 kA generator current is divided between $z = 2$ and 6 cm with 100 kA between $z = 4$ and 6 cm. The probe data in the rest of the r - z cross section determine the current channel between the outer and inner conductors, shown in Fig. 4. Data taken at $I_L = 100$ and 200 kA, shown by arrows in Fig. 2, determine the current streamlines during and after opening. Dashed lines in Fig. 4 show possible streamlines outside the data grid, consistent with the measured current I_L .

Figs. 4(a) and (b) show that current is conducted radially from the outer conductor to the inner conductor through the plasma. The current channel broadens quickly; after 36 ns the width of the current channel is about 4 cm. An effective resistivity can be calculated from this data using

$$\eta = \mu_0 \ell^2 / t, \quad (2)$$

where η is the resistivity in ohm-cm, $\mu_0 = 4\pi \times 10^{-11}$ H/cm, ℓ (cm) is the current channel width and t (s) is the penetration time. Using $\ell = 4$ cm and $t = 36$ ns, $\eta \approx 5$ ohm-cm, which is three orders of magnitude larger than the transverse Spitzer resistivity⁷ (for $T_e \sim 5$ eV). Buneman and ion-acoustic instabilities are possible causes of the enhanced collision frequency ($\sim 10^{10} \text{ s}^{-1}$). The current channel width is much larger than the collisionless skin depth; $c/\omega_{pe} = 0.1$ cm for $n_e = 3 \times 10^{13} \text{ cm}^{-3}$ (measured with an electric probe⁸).

A theoretical model of the PEOS that accounts for the observed switching behavior has been developed.⁹ In this theory, current is conducted in a bipolar, space-charge-limited fashion across a small gap at the cathode side of the PEOS. The maximum current that the PEOS can conduct (without opening)

is determined by the flux of ions to the cathode. The ion flux density is

$$\Gamma_i = n_i v_D, \quad (3)$$

where n_i is the ion density and v_D is the average ion drift velocity toward the cathode. The ratio of electron to ion current density across the gap (for the non-relativistic case) is

$$j_e/j_i = (M_i/Zm_e)^{1/2}, \quad (4)$$

where m_e (M_i) is the electron (ion) mass and Ze is the ion charge. The current through the plasma can increase until $j_i = \Gamma_i Ze$. A further increase in current causes the cathode gap to open, effectively increasing the ion current. This process is termed erosion of the plasma. During the erosion phase current begins to flow to the load. When the magnetic field in the gap is large enough to begin magnetic insulation of the cathode electrons, the ion current is larger than the value predicted by Eq. (4), similar to the enhancement that occurs in ion diodes.¹⁰ This enhanced ion current causes the gap to open faster, accounting for the observed fast switching. With this large gap, the switch current is effectively cut off due to magnetic insulation of the electrons, leaving only a small ion current flowing across the gap.

The broadening of the current channel can be explained by this model, because the ion flux imposes a current density limit at the cathode during the conduction phase. If the current increases with a constant ion current density, $j_i = \Gamma_i Ze$, the current channel at the cathode will broaden. Using Eqs. (3) and (4), the electron current density limit is:

$$j_e < n_i v_{De} (ZM_i/m_e)^{1/2} . \quad (5)$$

The plasma ions are mostly C^{++} ,⁸ so that $j_i/j_e \sim 0.01$, and the expression in Eq. (5) approximates the total current density, $j \sim j_e$. An equation for the current channel width, $\ell(t)$, is found using $I = 2\pi r_c \ell j$, where r_c is the cathode radius and I is the total switch current. Solving for ℓ gives

$$\ell(t) = \frac{I(t)}{2\pi r_c n_i v_{De}} \left(\frac{m_e}{ZM_i} \right)^{1/2} . \quad (6)$$

For the Gamble I experiment, $Z = 2$, $n_i \approx 1.5 \times 10^{13} \text{ cm}^{-3}$ and $v_D \approx 6 \times 10^6 \text{ cm/s}$.⁸ Eq. (6) then predicts $\ell = 1 \text{ cm}$ when $I = 37 \text{ kA}$, $\ell = 3 \text{ cm}$ when $I = 130 \text{ kA}$. This is consistent with the measured current channel width in the plasma [Figs. 4(a) and (b)]. Some deviation from this simple calculation is expected because of the known nonuniformity in $r_i(z)$ along the 6 cm switch length.⁸ Enhanced plasma resistivity would allow the current channel width in the plasma to follow the width of the current channel at the cathode. This resistivity may be the result of instabilities caused by high velocity electrons from the cathode that stream past the plasma ions.

The current channel is accelerated in the z direction because of $j \times B$ forces during the 40 ns conduction period. The plasma boundary on the generator side of the PEOS is near $z = 0$ before the generator is fired. This boundary evidently moves 2 cm in the axial direction (Fig. 4) while the front of the current channel moves 6 cm (because of diffusion) in the same time period.

Figs. 4(c) and (d) show that the current is diverted to the load when the current path is disrupted near the inner conductor. This is attributed to the

increasing radial gap between the plasma and the cathode. The mechanism for gap formation is assumed to be erosion of the plasma and not magnetic pressure; magnetic forces in the radial direction are small between $t = 36$ ns and 46 ns (Fig. 4). After opening, a large fraction of the current continues to flow through the plasma. These plasma currents decay in about 100 ns (Fig. 3), a much longer time than the observed penetration time. This decrease in resistivity is consistent with magnetic insulation of the emitted cathode electrons which no longer drive instabilities in the plasma. The small gap size (<0.5 cm) indicated in Fig. 4(d) is due to the low impedance load used in these experiments; numerical modeling shows much larger gap formation when finite impedance loads (diodes) are employed.

The magnetic field measurements presented here give a picture of the current flow pattern in a PEOS. The current channel through the plasma broadens rapidly and becomes much larger than the skin depth, c/ω_{pe} . The inferred resistivity is anomalously large. The channel width is consistent with a current density limit determined by the ion flux to the cathode. Rapid switching occurs when a gap opens at the cathode side of the PEOS. Radial $j \times B$ forces are small at the time the gap opens, so erosion of the plasma is assumed to be the dominant opening mechanism. After opening, current continues to flow through the plasma but magnetic insulation prevents electron conduction across the gap.

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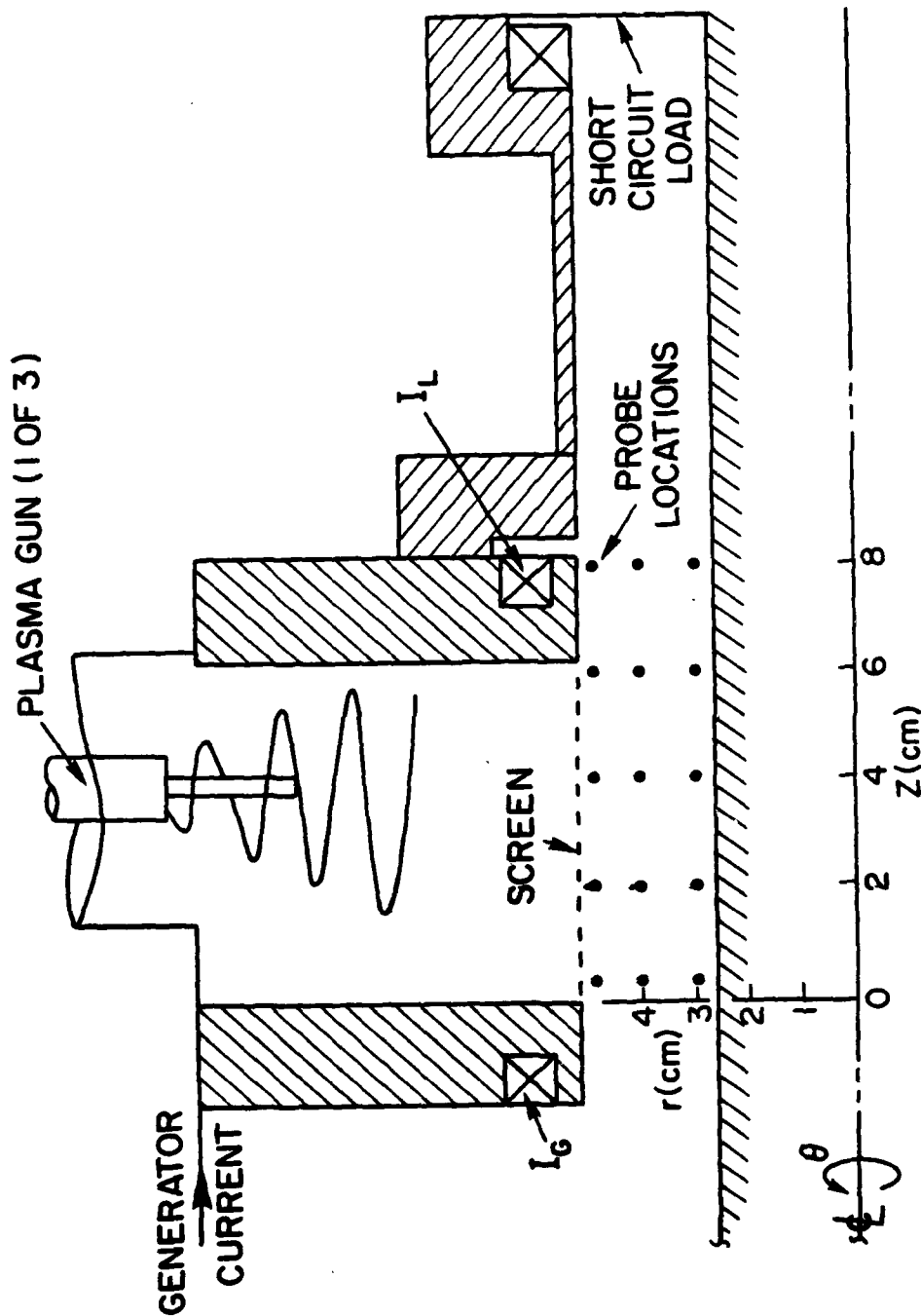


Fig. 1 — Gamble 1 PEOS Experiment: Rogowski loops measure the current on the generator side of the switch, I_G , and the load side of the switch, I_L . Dots indicate the data grid sampled to determine the current distribution.

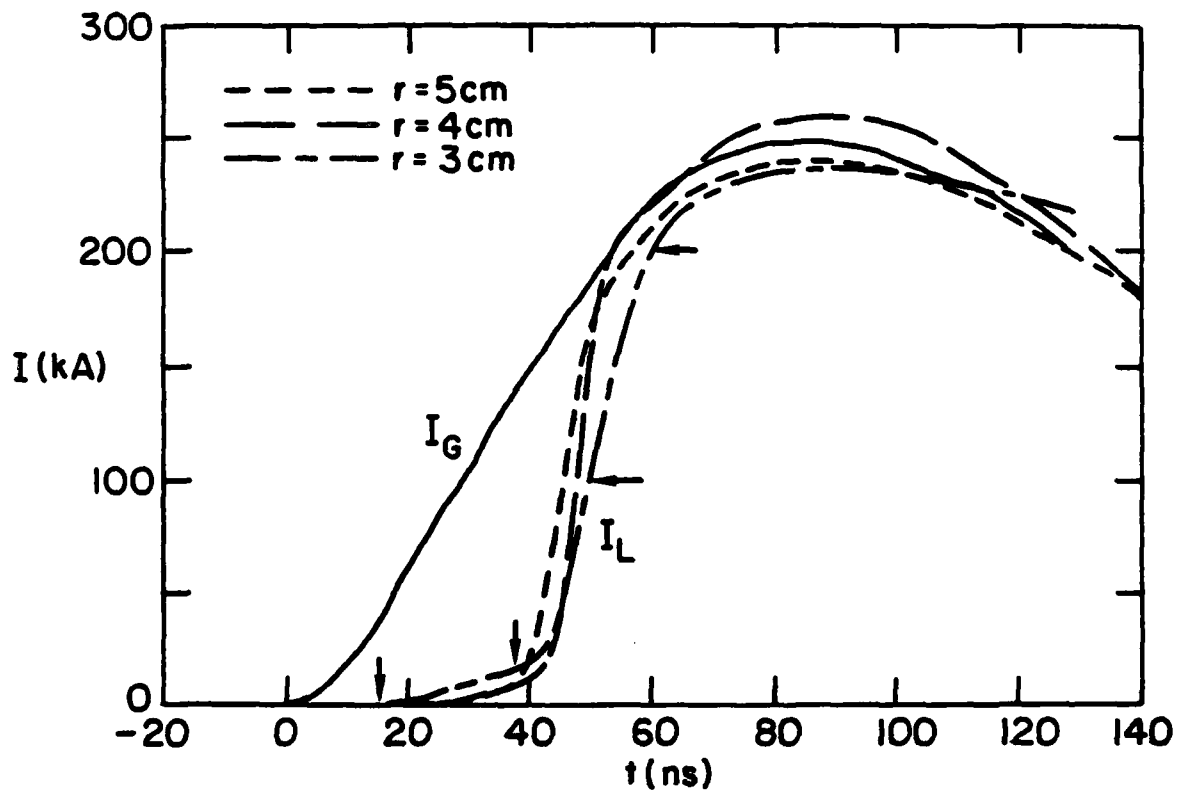


Fig. 2— Current Measurements: Three load currents (I_L) and one generator current (I_G) are shown, illustrating the fast opening property of the PEOS. The I_L measurements are for different radial locations of the probe array. The four I_L values marked in the figure are analyzed to determine the current distribution.

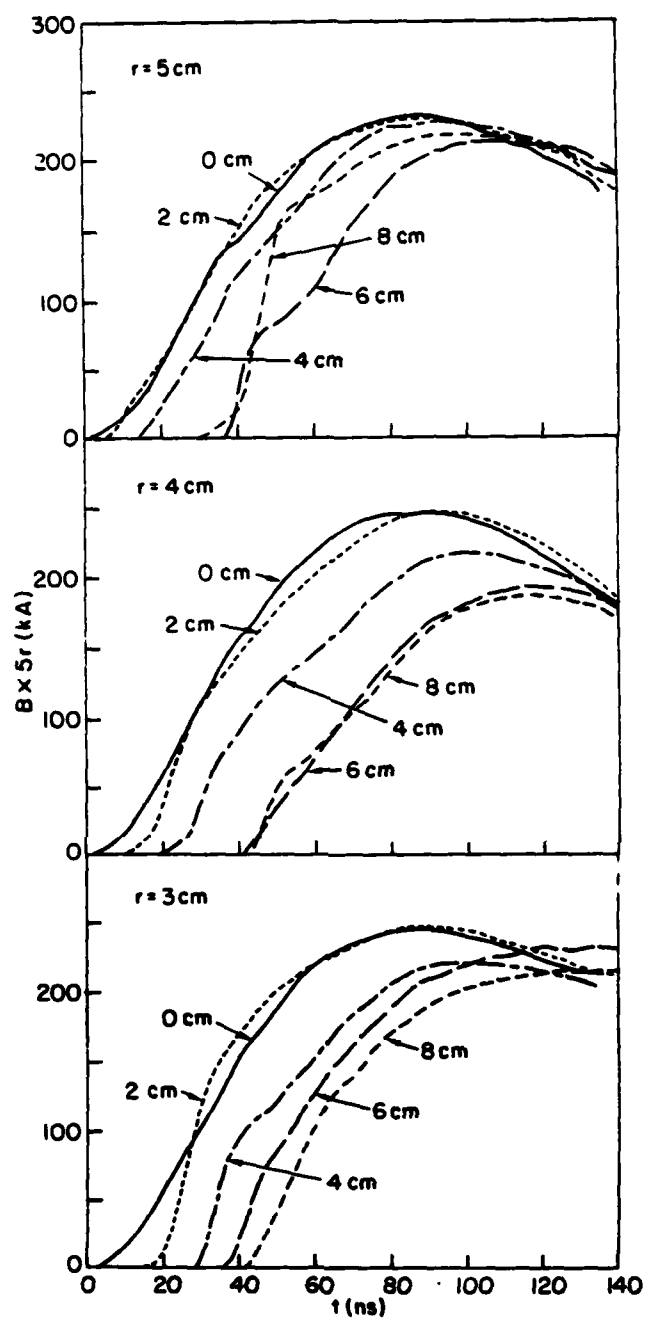


Fig. 3 — Field measurements are shown with the probe array at $r = 3, 4$, and 5 cm. The probe signals are normalized to the system currents using $I = B_\theta \times 5r$.

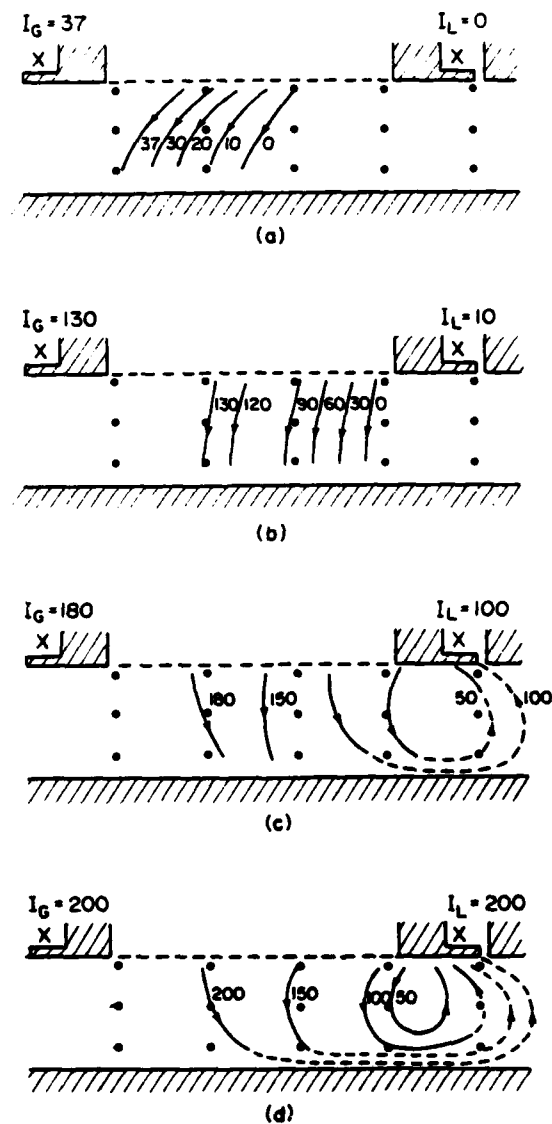


Fig. 4 — Current streamlines through the plasma are drawn (using the data in Figure 3), at the four times indicated in Figure 2. Each diagram shows the I_G and I_L values (in kA). (a) and (b): Current is conducted in the radial direction over a broad channel while the PEOS is "closed." (c) The current is diverted to the load near the downstream end of the switch region. (d) The current flows through the plasma within 0.5 cm of the inner conductor.

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